



$$3. \quad \frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} = u f\left(\frac{u}{w}\right), \quad \frac{\partial^2 w}{\partial x^2} + \frac{\partial^2 w}{\partial y^2} = w g\left(\frac{u}{w}\right).$$

1°. Solution in the form of the product of functions with different arguments, periodic in the space variable (a similar solution can be obtained by swapping x and y):

$$u = [C_1 \sin(kx) + C_2 \cos(kx)]\varphi(y),$$

$$w = [C_1 \sin(kx) + C_2 \cos(kx)]\psi(y),$$

where C_1, C_2 , and k are arbitrary constants, and the functions $\varphi = \varphi(y)$ and $\psi = \psi(y)$ are determined by the system of ordinary differential equations

$$\varphi''_{yy} = k^2 \varphi + \varphi f(\varphi/\psi),$$

$$\psi''_{yy} = k^2 \psi + \psi g(\varphi/\psi).$$

2°. Solution in multiplicative form:

$$u = [C_1 \exp(kx) + C_2 \exp(-kx)]U(y),$$

$$w = [C_1 \exp(kx) + C_2 \exp(-kx)]W(y),$$

where C_1, C_2 , and k are arbitrary constants, and the functions $U = U(y)$ and $W = W(y)$ are determined by the system of ordinary differential equations

$$U''_{yy} = -k^2 U + U f(U/W),$$

$$W''_{yy} = -k^2 W + W g(U/W).$$

3°. Degenerate solution in multiplicative form:

$$u = (C_1 x + C_2)U(y),$$

$$w = (C_1 x + C_2)W(y),$$

where C_1 and C_2 are arbitrary constants, and the function $U = U(y)$ and $W = W(y)$ are determined by the system of ordinary differential equations

$$U''_{yy} = U f(U/W),$$

$$W''_{yy} = W g(U/W).$$

Remark. In Items 1°–3°, the functions f and g can be dependent on y .

4°. Solution in multiplicative form:

$$u = e^{a_1 x + b_1 y} \xi(z), \quad w = e^{a_1 x + b_1 y} \eta(z), \quad z = a_2 x + b_2 y,$$

where a_1, a_2, b_1 , and b_2 are arbitrary constants, and the functions $\xi = \xi(z)$ and $\eta = \eta(z)$ are determined by the system of ordinary differential equations

$$(a_2^2 + b_2^2)\xi''_{zz} + 2(a_1 a_2 + b_1 b_2)\xi'_z + (a_1^2 + b_1^2)\xi = \xi f(\xi/\eta),$$

$$(a_2^2 + b_2^2)\eta''_{zz} + 2(a_1 a_2 + b_1 b_2)\eta'_z + (a_1^2 + b_1^2)\eta = \eta g(\xi/\eta).$$

5°. Solution:

$$u = k\theta(x, y), \quad w = \theta(x, y),$$

where k is a root of the algebraic (transcendental) equation $f(k) = g(k)$, and the function $\theta = \theta(x, y)$ satisfies the linear Helmholtz equation

$$\frac{\partial^2 \theta}{\partial x^2} + \frac{\partial^2 \theta}{\partial y^2} = f(k)\theta.$$

For its exact solutions see the “Handbook of Linear Partial Differential Equations for Engineers and Scientists” by A. D. Polyanin (2002).