



$$1. \quad \frac{\partial^2 u}{\partial t^2} = \frac{a}{x^n} \frac{\partial}{\partial x} \left( x^n \frac{\partial u}{\partial x} \right) + u f(bu - cw) + g(bu - cw),$$

$$\frac{\partial^2 w}{\partial t^2} = \frac{a}{x^n} \frac{\partial}{\partial x} \left( x^n \frac{\partial w}{\partial x} \right) + w f(bu - cw) + h(bu - cw).$$

1°. Solution:

$$u = \varphi(t) + c\theta(x, t), \quad w = \psi(t) + b\theta(x, t),$$

where  $\varphi = \varphi(t)$  and  $\psi = \psi(t)$  are determined by the system of ordinary differential equations

$$\begin{aligned} \varphi''_{tt} &= \varphi f(b\varphi - c\psi) + g(b\varphi - c\psi), \\ \psi''_{tt} &= \psi f(b\varphi - c\psi) + h(b\varphi - c\psi), \end{aligned}$$

and the function  $\theta = \theta(x, t)$  satisfies the linear equation

$$\frac{\partial^2 \theta}{\partial t^2} = \frac{a}{x^n} \frac{\partial}{\partial x} \left( x^n \frac{\partial \theta}{\partial x} \right) + f(b\varphi - c\psi)\theta.$$

For  $f = \text{const}$ , this equation can be solved by the method of separation of variables.

2°. Let us multiply the first equation by  $b$  and add it to the second equation multiplied by  $-c$  to obtain

$$\frac{\partial^2 \zeta}{\partial t^2} = \frac{a}{x^n} \frac{\partial}{\partial x} \left( x^n \frac{\partial \zeta}{\partial x} \right) + \zeta f(\zeta) + bg(\zeta) - ch(\zeta), \quad \zeta = bu - cw. \quad (1)$$

This equation will be treated in conjunction with the first equation of the original system,

$$\frac{\partial^2 u}{\partial t^2} = \frac{a}{x^n} \frac{\partial}{\partial x} \left( x^n \frac{\partial u}{\partial x} \right) + u f(\zeta) + g(\zeta). \quad (2)$$

Equation (1) can be treated separately. Given a solution  $\zeta = \zeta(x, t)$  of equation (1), the function  $u = u(x_1, \dots, x_n, t)$  can be found by solving the linear equation (2), and the function  $w = w(x_1, \dots, x_n, t)$  is determined by the formula  $w = (bu - \zeta)/c$ .

Note three important cases:

(i) In the general case, equation (1) admits a space-homogeneous solution  $\zeta = \zeta(t)$ . The corresponding solution of the original system is given in Item 1° in a different form.

(ii) In the general case, equation (1) admits a stationary  $\zeta = \zeta(x)$ ; the corresponding exact solutions of equation (3) have the forms  $u = u_0(x) + \sum e^{-\beta_n t} u_n(x)$  and  $u = u_0(x) + \sum \cos(\beta_n t) u_n^{(1)}(x) + \sum \sin(\beta_n t) u_n^{(2)}(x)$ .

(iii) If the condition  $\zeta f(t, \zeta) + bg(t, \zeta) - ch(t, \zeta) = k_1 \zeta + k_0$  holds, equation (1) is linear,

$$\frac{\partial^2 \zeta}{\partial t^2} = \frac{a}{x^n} \frac{\partial}{\partial x} \left( x^n \frac{\partial \zeta}{\partial x} \right) + k_1 \zeta + k_0,$$

and can be solved using the method of separation of variables.